

A Study of W_6 -Curvature Tensor in Lp-Sasakian Manifold

Wilson Kamami Wanjiru

Abstract: Pokhariyah have introduced some curvature tensors to study their properties. In this paper properties of W_6 -curvature tensor are studied in Lp- Sasakian manifold and some theorem proved

I. INTRODUCTION

An n-dimensional differentiable manifold M is said to be Lorentzian Para Sasakian manifold if it admits a (1, 1) tensor field F, a covariant (C^∞) vector field T, a C^∞ 1 form A and a Lorentzian metric g which satisfies (Matsumoto and Mihai, 1998)

$$(1.1) \quad A(T) = -1$$

$$(1.2) \quad \nabla_X T = X + A(X)T, \text{ where } \nabla_X = f(X).$$

$$(1.3) \quad g(X, Y) = g(X, Y) + A(X)A(Y)$$

$$(1.4) \quad g(X, T) = A(X)$$

$$(1.5) \quad (\Delta_X F)(Y) = g(X, Y) + A(X)A(Y)T + X + A(X)TA(Y),$$

where $\Delta_X T = X$ and Δ de-note operator covariant differentiation with respect to the Lorentzian metric g.

In LP-Sasakian manifold M with structure (F,T,A,g) we have

$$(1.6) \quad T = \phi.A(X) = \phi$$

$$(1.7) \quad \text{rank}(F) = n - 1.$$

Furthermore, if we put

$$(1.8) \quad F(X, Y) = g(X, Y),$$

then tensor field $F(X, Y)$ is symmetric in X and Y.

In n-dimensional LP-Sasakian manifold with structure (F,T,A,g) we have

$$(1.9) \quad R(X, Y, Z, T) = g(Y, Z)A(X) - g(X, Z)A(Y)$$

$$(1.10) \quad Ric(X, T) = (n - 1)A(X)$$

$$(1.11) \quad R(X, Y, Z, U) = R(X, Y, Z, U) + 2A(Z)[g(X, U)A(Y) - g(Y, U)A(X)] + 2A(U)[A(Y)g(X, Z) - A(X)g(Y, Z)] + F(Y, U)F(X, Z) - F(X, U)F(Y, Z) + g(Y, Z)g(X, U) - g(X, Z)g(Y, U),$$

where $R(X, Y, Z)$ denote curvature and $Ric(X, Y)$ denote Ricci tensor.

Pokhariyah (1982) have defined a tensor

$$(1.12) \quad W_6(X, Y, Z, U) = R(X, Y, Z, U) + \frac{1}{n-1} [g(X, Y)Ric(Z, U) - g(X, U)Ric(Y, Z)]$$

we break this tensor into symmetric P and skew symmetric Q parts in X and Y as follows.

$$\begin{aligned} P(X, Y, Z, U) &= \frac{1}{2} [W_6(X, Y, Z, U) + W_6(Y, X, Z, U)] \\ &= \frac{1}{2} [R(X, Y, Z, U) + \frac{1}{n-1} [g(X, Y)Ric(Z, U) - g(X, U)Ric(Y, Z)] \\ &\quad + R(Y, X, Z, U) + \frac{1}{n-1} [g(Y, X)Ric(Z, U) - g(Y, U)Ric(X, Z)]] \\ &= \frac{1}{2} [R(X, Y, Z, U) + \frac{1}{2} R(Y, X, Z, U) + \frac{1}{2(n-1)} [g(X, Y) \\ &\quad Ric(Z, U) - g(X, U)Ric(Y, Z) + g(Y, X)Ric(Z, U) - g(Y, U) \\ &\quad Ric(X, Z)]] \\ &= \frac{1}{2(n-1)} [g(X, Y)Ric(Z, U) - g(X, U)Ric(Y, Z) + g(Y, X) \\ &\quad Ric(Z, U) - g(Y, U)Ric(X, Z)] \end{aligned}$$

Thus we have

$$(1.13) \quad P(X, Y, Z, U) = \frac{1}{2(n-1)} [2g(X, Y)Ric(Z, U) - g(X, U)Ric(Y, Z) - g(Y, U)Ric(X, Z)].$$

Now we take a look at skew-symmetric part Q

$$\begin{aligned} Q(X, Y, Z, U) &= \frac{1}{2} [W_6(X, Y, Z, U) - W_6(Y, X, Z, U)] \\ &= \frac{1}{2} [R(X, Y, Z, U) + \frac{1}{(n-1)} [g(X, Y)Ric(Z, U) - g(X, U)Ric(Y, Z)] \\ &\quad - R(Y, X, Z, U) - \frac{1}{(n-1)} [g(Y, X)Ric(Z, U) - g(Y, U)Ric(X, Z)]] \\ &= \frac{1}{2} [R(X, Y, Z, U) - \frac{1}{2} R(Y, X, Z, U) + \frac{1}{2(n-1)} [g(X, Y)Ric(Z, U) \\ &\quad - g(X, U)Ric(Y, Z) - g(Y, X)Ric(Z, U) + g(Y, U)Ric(X, Z)]] \\ &= R(X, Y, Z, U) + \frac{1}{2(n-1)} [g(X, Y)Ric(Z, U) - g(X, U)Ric(Y, Z)] - \\ &\quad g(Y, X)Ric(Z, U) + g(Y, U)Ric(X, Z)] \end{aligned}$$

Thus we have

$$(1.14) \quad Q(X, Y, Z, U) = R(X, Y, Z, U) - \frac{1}{2(n-1)} [g(X, U)Ric(Y, Z) - g(Y, U)Ric(X, Z)].$$

II. LP-SASAKIAN MANIFOLD

In this section we study properties of W_6, P, Q curvature tensors in LP-sasakian manifold.

Theorem 2.1

In an n-dimensional LP-Sasakian manifold we have

$$(2.1)a. W_6(T, Y, Z, T) = g(Y, Z) + \frac{1}{(n-1)} Ric(Y, Z)$$

$$(2.1)b. W_6(X, Y, T) = YA(X) - \frac{2-n}{(n-1)}$$

$$(2.1)c. W_6(T, Y, T) = Y - \frac{n-2}{(n-1)}$$

Proof (2.1)a

Putting U=T in (1.12) we get,

$${}^J W_6(X, Y, Z, T) = {}^J R(X, Y, Z, T) + \frac{1}{(n-1)} [g(X, Y) Ric(Z, T) - g(X, T) Ric(Y, Z)]$$

Using (1.4), we get

$${}^J W_6(X, Y, Z, T) = {}^J R(X, Y, Z, T) + \frac{1}{(n-1)} [g(X, Y) Ric(Z, T) - A(X) Ric(Y, Z)]$$

Using (1.9), we get

$${}^J W_6(X, Y, Z, T) = g(Y, Z) A(X) - g(X, Z) A(Y) + \frac{1}{(n-1)} [g(X, Y) Ric(Z, T) - A(X) Ric(Y, Z)]$$

Using (1.10), we get

$${}^J W_6(X, Y, Z, T) = g(Y, Z) A(X) - g(X, Z) A(Y) + \frac{1}{(n-1)} [g(X, Y)(n-1)A(Z) - A(X) Ric(Y, Z)]$$

$$(2.2) = g(Y, Z) A(X) - g(X, Z) A(Y) + g(X, Y) A(Z) - A(X) \frac{1}{(n-1)} Ric(Y, Z)$$

Putting X=T in(2.2) we get

$${}^J W_6(T, Y, Z, T) = g(Y, Z) A(T) - g(T, Z) A(Y) + g(T, Y) A(Z) - A(T) \frac{1}{(n-1)} Ric(Y, Z)$$

Using (1.1), we get

$${}^J W_6(T, Y, Z, T) = g(Y, Z) g(T, Z) A(Y) + g(T, Y) A(Z) + \frac{1}{(n-1)} Ric(Y, Z)$$

Again using (1.4), we get

$${}^J W_6(T, Y, Z, T) = g(Y, Z) A(Z) A(Y) + A(Y) A(Z) + \frac{1}{(n-1)} Ric(Y, Z)$$

$${}^J W_6(T, Y, Z, T) = g(Y, Z) + \frac{1}{(n-1)} Ric(Y, Z) \dots\dots\dots$$

Hence proved.

Proof (2.1)b

${}^J W_6(X, Y, Z, U) = g(W_6(X, Y, Z), U)$ and (1.12), we have

$$W_6(X, Y, Z) = R(X, Y, Z) + \frac{1}{(n-1)} [g(X, Z) Y - X Ric(Y, Z)]$$

Putting T=Z

$$W_6(X, Y, T) = R(X, Y, T) + \frac{1}{(n-1)} [g(X, T) Y - X Ric(Y, T)]$$

Using XA(Y)-YA(X) and (1.4) (1.10), we get

$$W_6(X, Y, T) = XA(Y) - YA(X) + \frac{1}{(n-1)} [A(X) Y - X(n-1)A(Y)]$$

$$W_6(X, Y, T) = XA(Y) - YA(X) + \frac{1}{(n-1)} A(X) Y - XA(Y)$$

$$W_6(X, Y, T) = -YA(X) + \frac{1}{(n-1)} A(X) Y$$

$$W_6(X, Y, T) = YA(X) - \frac{2-n}{(n-1)} \quad \text{Hence proved.}$$

Proof (2.1) c

Putting X=T in (2.1)2, we get

$$W_6(T, Y, T) = YA(T) - \frac{2-n}{(n-1)}$$

Using (1.1) we get

$$W_6(T, Y, T) = -Y - \frac{2-n}{(n-1)}$$

$$W_6(T, Y, T) = Y - \frac{n-2}{(n-1)} \quad \text{Hence proved.}$$

Theorem 2.2

In an n-dimensional LP-Sasakian manifold P tensor field satisfies

$$(2.2)a. P(X, Y, Z, T) = g(X, Y) A(Z) - \frac{1}{2(n-1)} \{A(X) Ric(Y, Z) + A(Y) Ric(X, Z)\}$$

$$(2.2)b. P(T, Y, Z, U) = -\frac{1}{2} g(Y, U) A(Z) + \frac{1}{2(n-1)} [2A(Y) Ric(Z, U) - A(U) Ric(Y, Z)]$$

$$(2.2)c. P(T, Y, Z, T) = \frac{1}{2} [A(Y) A(Z) + \frac{1}{(n-1)} Ric(Y, Z)]$$

Proof (2.2)a

Using (1.13) and putting T=U, we have

$${}^J P(X, Y, Z, T) = \frac{1}{2(n-1)} [g(X, Y) Ric(Z, T) g(X, T) Ric(Y, Z)] + g(Y, X) Ric(Z, T) - g(Y, T) Ric(X, Z)]$$

Using (1.4) and (1.10), we get

$$= \frac{1}{2(n-1)} [g(X, Y)(n-1)A(Z) - A(X) Ric(Y, Z)] + g(Y, X)(n-1)A(Z) - A(Y) Ric(X, Z]$$

$$= \frac{1}{2} [g(Y, X) A(Z) + g(X, Y) A(Z)] - \frac{1}{2(n-1)} [A(X) Ric(Y, Z) - A(Y) Ric(X, Z)]$$

$$= g(X, Y) A(Z) - \frac{1}{2(n-1)} [A(X) Ric(Y, Z) + A(Y) Ric(X, Z)].$$

Hence proved.

Proof (2.2)b

Using (1.13) and putting T=X, we have

$${}^J P(T, Y, Z, U) = \frac{1}{2(n-1)} [2g(T, Y) Ric(Z, U) - g(T, U) Ric(Y, Z) - g(Y, U) Ric(T, Z)]$$

Using (1.4) and (1.10), we have

$${}^J P(T, Y, Z, U) = \frac{1}{2(n-1)} [2A(Y) Ric(Z, U) - A(U) Ric(Y, Z) - g(Y, U)(n-1)A(Z)]$$

$${}^J P(T, Y, Z, U) = -\frac{1}{2} g(Y, U) A(Z) + \frac{1}{2(n-1)} [2A(Y) Ric(Z, U) - A(U) Ric(Y, Z)]$$

Hence proved.

Proof (2.2)c

Putting X=T in (2.2)a, we get

$${}^J P(T, Y, Z, T) = g(T, Y) A(Z) - \frac{1}{2(n-1)} [A(T) Ric(Y, Z) + A(Y) Ric(T, Z)]$$

Using (1.1), (1.4) and (1.10) we have

$${}^J P(T, Y, Z, T) = A(Y) A(Z) - \frac{1}{2(n-1)} [Ric(Y, Z) - A(Y)(n-1)A(Z)]$$

$${}^J P(T, Y, Z, T) = A(Y) A(Z) - \frac{1}{2} A(Y) A(Z) + \frac{1}{2(n-1)} Ric(Y, Z)$$

$${}^J P(T, Y, Z, T) = \frac{1}{2} [A(Y) A(Z) + \frac{1}{(n-1)} Ric(Y, Z)].$$

Hence proved.

Theorem 2.3

In an n-dimensional LP-Sasakian manifold Q tensor field satisfies

(2.3)a.

$${}^J Q(X, Y, Z, T) = A(X) [g(Y, Z) - \frac{1}{2(n-1)} Ric(Y, Z)] - A(Y) [g(X, Z) - \frac{1}{2(n-1)} Ric(X, Z)]$$

$$(2.3)b. {}^J Q(T, Y, Z, U) = A(U) [g(Y, Z) - \frac{1}{2(n-1)} Ric(Y, Z)] - \frac{1}{2} g(Y, U) A(Z)$$

$$(2.3)c. {}^J Q(T, Y, Z, T) = -g(Y, Z) + \frac{1}{2} [\frac{1}{(n-1)} Ric(Y, Z) - A(Y) A(Z)]$$

Proof (2.3)a

Using (1.14) and putting T=U, we have

$${}^J Q(X, Y, Z, T) = R(X, Y, Z, T) - \frac{1}{2(n-1)} [+g(X, T) Ric(Y, Z) - g(Y, T) Ric(X, Z)]$$

Using (1.4) and (1.9), we have

$${}^J Q(X, Y, Z, T) = g(Y, Z) A(X) - g(X, Z) A(Y) - \frac{1}{2(n-1)} [+A(X) Ric(Y, Z) - A(Y) Ric(X, Z)]$$

$${}^J Q(X, Y, Z, T) = A(X) [g(Y, Z) - \frac{1}{2(n-1)} Ric(Y, Z)] - A(Y) [g(X, Z) - \frac{1}{2(n-1)} Ric(X, Z)].$$

Hence Proved.

Proof (2.3)b

Using (1.14) and putting T=X, we have

$${}^J Q(T, Y, Z, U) = R(T, Y, Z, U) - \frac{1}{2(n-1)} [g(T, U) Ric(Y, Z) - g(Y, U) Ric(T, Z)]$$

Using (1.4), (1.9), (1.10) we have

$${}^J Q(T, Y, Z, U) = g(Y, Z) A(U) - g(Y, U) A(Z) - \frac{1}{2(n-1)} [A(U) Ric(Y, Z) - g(Y, U)(n-1)A(Z)]$$

$${}^J Q(T, Y, Z, U) = A(U) [g(Y, Z) - \frac{1}{2(n-1)} Ric(Y, Z)] - \frac{1}{2} g(Y, U) A(Z).$$

Hence proved.

Proof (2.3)c

Let X=T in (2.3)a

$${}^J Q(T, Y, Z, T) = A(T) [g(Y, Z) - \frac{1}{2(n-1)} Ric(Y, Z)] - A(Y) [g(T, Z) - \frac{1}{2(n-1)} Ric(T, Z)]$$

Using (1.1), (1.9), (1.10), we have

$$Q(T, Y, Z, T) = -[g(Y, Z) - \frac{1}{2(n-1)} Ric(Y, Z)] - A(Y) [A(Z) - \frac{1}{2(n-1)} (n-1)A(Z)]$$

$$Q(T, Y, Z, T) = -g(Y, Z) + \frac{1}{2(n-1)} Ric(Y, Z) - A(Y) [A(Z) + \frac{1}{2} A(Y) A(Z)]$$

$$Q(T, Y, Z, T) = -g(Y, Z) + \frac{1}{2} [\frac{1}{(n-1)} Ric(Y, Z) - A(Y) A(Z)].$$

Hence proved.

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